Haleh Mohammadian

Email: hmohammadian@ucdavis.edu Website: https://halehossadat.github.io/

Mobile: +1(530)231-2178

EDUCATION

University of California, Davis

Davis, USA

Doctoral of Computer Science and Information Sciences

Jan 2023 - present

Sharif University of Technology

Tehran, Iran

Master of Computer Science - Scientific Computing

Sep 2016 - Sep 2019

o Thesis: 3D Reconstruction and Extrinsic Parameters Calibration of Non-Overlapping Cameras

University of Isfahan

Isfahan, Iran

Bachelor of Computer Science

Sep 2012 - Jul 2016

• Final Project Title: Chebfun Softwares

Class rank 1GPA: 18.36/20.00

Research Experience

Guest Researcher

Saarbrücken, Germany

 $\bullet \ \ Artificial \ Intelligence \ aided \ Design \ and \ Manufacturing \ Group,$

Oct 2020 - May 2022

Max Planck Institute for Informatics

- New computational method for designing geometries with structured release profile
- o Supervision of Dr. Vahid Babaei
- o Collaboration of **Prof. Julian Panetta** at University of California, Davis, USA.
- o Physics-based simulation of dissolution process
- o Inverse design using nonlinear optimization and adjoint methods
- Measure release profile of dissolution process using novel capture system
- Evaluate method with real data experiments
- Fabrication using fused deposition modeling 3D printers
- $\circ\,$ This project was published in ACM Transactions on Graphics
- This project was presented in ACM SIGGRAPH ASIA 2022

Researcher Tehran, Iran

• Math Laboratory

 $July\ 2017$ - $September\ 2019$

Sharif University of Technology

- Study of non-rigid structure from motion problems.
- Supervision of Prof.Razvan and Prof.Moghadasi
- o Consult of **Dr.Mostafa Kamali Tabrizi**.
- $\circ~$ Shape-basis vs trajectory-basis nonrigid structures
- The deformable objects generally vary their shapes over time, so the number of unknown parameters increases dramatically in compare to rigid Structure from motion problems.
- This project is published as part of my master thesis

Internship Singapore, Singapore

• Computer Vision and Robotic Perception

July 2018 - March 2019

National University of Singapore

- Novel method for calibrating extrinsic parameters of non-overlapping cameras
- Supervision of Prof.Gim Hee Lee
- Formulate problem using light and shadow geometry as structure from motion problem
- o Bundle adjustment as solving nonlinear least square problem using Google Ceres
- o Evaluate method with synthetic data and real experiments
- This project is published as part of my master thesis

Team Member Isfahan, Iran July 2008-June 2010

2015

Parmida team member

Farzanegane Amin High School

- Design junior rescue and junior soccer robots for IranOpen competitions.
- o Design electrical circuits and PCB using Proteus software
- Design mechanical structure of robots using AutoCAD
- o Programming robots using Assembly language
- o Supervision of Mohammad Nabi and Behrooz Farid

TEACHING EXPERIENCE

Teaching Assistant

• Numerical Linear Algebra Matlab Course

University of Isfahan

- Teach undergraduate students MATLAB programming language
- o Implementing numerical algebraic algorithms
- o Part of Numerical Linear Algebra undergraduate course

TECHNICAL SKILLS

• Programming Languages: C, C++, Python, MATLAB, LaTeX

• Operating Systems: Linux

3D CAD Softwares: OpenSCAD

• Verison Control Systems: Git

Research Interests

- Computer Graphics
- Physics-based Simulation
- Computational Fabrication
- 3D Computer Vision
- 3D Reconstruction
- Multiple View Geometry
- Numerical Analysis

Awards

• Accepted in M.Sc Program without Entrance Exam as an Exceptional Talents	2016
• Ranked 1st among B.Sc graduates in Computer Science at University of Isfahan	2016
• Rank 3rd in IUT RaadCup, Junior Soccer League	2010
• Qualification in RoboCup IranOpen, Junior Soccer League	2009
• Qualification in RoboCup IranOpen, Junior Rescue League	2009
• Accepted in National Organization for Development of Exceptional Talent High School	2007

PUBLICATIONS

Shape from Release: Inverse Design and Fabrication of Controlled Release Structures. Julian Panetta, Haleh Mohammadian, Emiliano Luci, Vahid Babaei, ACM Transactions on Graphics (ACM SIGGRAPH ASIA, 2022).